EXAMINATION

Modeling and Analysis of Concurrent Systems 2

course code: 192135320

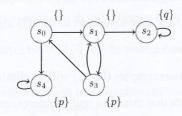
date: January 30, 2015 time: 13.45–16.45

General

- This is an 'open book' exam. Printed handouts (slides, articles, book chapters) may be used, but no handwritten notes, previous examinations, or their answers.
- This exam consists of 3 pages with 7 questions. In total 100 points can be earned:
 - 70 points with the material of the main lectures, (Question 1-4)
 - 30 points with the material from the research papers, (Question 5-7).

PART I: Basic Lectures

In Question 1 and 2, the following Kripke structure is considered:



Question 1 (16 points)

Consider the following formulas from CTL*:

- 1) $\mathbf{AG}q$
- 2) **A FG**¬q
- 3) $\mathbf{EF} \mathbf{AG} q$
- A. Which of the three formulas above are in LTL and which are in CTL? (no explanation needed)
- B. Which of the formulas above hold in s_0 , according to normal CTL* semantics? (short explanation)
- C. Next, we consider a single fairness constraint p, i.e. $\{\{s_3, s_4\}\}$. Indicate which of the formulas above hold in s_0 , using the *fair* CTL* semantics. (short explanation)

Question 2 (18 points)

Next, we apply the symbolic model checking algorithm on the previous Kripke structure.

- A. Rewrite the formula $\mathbf{AG} \neg q$ into the proper $\mathbf{EX}, \mathbf{EU}, \mathbf{EG}$ fragment.
- B. Demonstrate the iterations of the symbolic model checking algorithm when computing the set of states in the previous Kripke structure that satisfy $\mathbf{AG} \neg q$. (It is not required to present BDD notation.)
- C. The states that satisfy $\mathbf{EG} \neg q$ under fairness constraint $\{p\}$ can be computed by a nested fixed point computation. Write down the precise fixed point expression, using least (μ) and/or greatest (ν) fixed point operators? (It is not required to evaluate it.)

Question 3 (18 points)

- A. Provide the OBDD-representations of the following two formulas, using variable ordering p < q < r:
 - $p \leftrightarrow q \leftrightarrow r$ and
 - $(p \leftrightarrow q) \land r$.
- B. The recursive BddApplyAnd function can be used to compute the conjuction (\land) of these two BDDs.
 - (i) Number the nodes in your BDDs and draw the call graph of BddApplyAnd.
 - (ii) Indicate clearly at which point(s) a result from the Operations Cache is reused.
- C. Explain why the Operations Cache is required to compute BddApplyAnd in polynomial time.

Question 4 (18 points)

We consider a run of the IC3 algorithm for incremental inductive verification, with set of initial states I and set of bad states $\neg p$. After three iterations, we found $I = F_0 \subseteq F_1 \subseteq F_2 \subseteq F_3 \subseteq p$. Assume that we find some $s \in F_3$ with $s \to t$ but $t \notin p$. In that case IC3 tries to remove s from F_3 and to propagate this back by removing predecessors of s from F_2 , etc.

- A. Draw this situation in a Venn diagram.
- B. Show that it follows from the four main invariants of the IC3 algorithm that $s \not lnF_2$.
- C. Is it possible that there is no predecessor of s in F_2 ? (short explanation)
- D. How does IC3 avoid that counterexamples (like s) will be eliminated one by one?
- E. Explain when IC3 can conclude that there is a real counterexample to $AG\neg p$.
- F. Explain when IC3 can conclude that the property $AG \neg p$ holds.

[SEE ALSO PAGE 3]

PART II: Student Lectures

This part considers the following research papers studied during the course:

- mcr Multi-core Reachability (Laarman, van de Pol, Weber) [Lecture 3]
 - clt Efficient State storage with Cleary Tables (Dillinger, Maniolis)
- Irn Learning to Divide and Conquer (Pasareanu, etal.)
- bmc Bounded Model Checking with SAT (Clarke, Biere, etal.)
- tpn Timed-Arc Petri Nets (Viesmose, Moesgaard etal.)
- car Counterexample-Guided Abstraction Refinement (Clarke, Grumberg etal.)
- smc Software Model Checking: the VeriSoft approach (Godefroid)

Question 5 (8 points)

Paper [Irn] uses the L^* learning algorithm in compositional verification. Indicate if the following statements are *right* or *wrong*.

- A. The L^* algorithm learns assumptions on the component to be verified
- B. The L^* algorithm learns the properties to be verified on the component
- C. The L^* algorithm learns assumptions on the environment of the component to be verified
- D. The L^* algorithm learns counter examples to the property to be verified

Question 6 (8 points)

Both papers [mcr] and [clt] discuss efficient hash table implementations. Indicate if the following statements are *right* or *wrong*?

- A. [clt] uses less memory than [mcr], because [clt] doesn't store full hash keys, while [mcr] does.
- B. Both [clt] and [mcr] use some variant of linear probing, because this helps to avoid cache misses.
- C. In [mcr], an inserted entry will always stay on the same position, while in [clt] inserted entries might move up or down by later insertions.
- D. Although not mentioned explicitly in [clt], that implementation must contain some locking primitive, like the compare-and-swap operation, as used in [mcr].

Question 7 (14 points)

Many algorithms apply forward reachability, based on breadth-first-search from the initial state. Indicate which of the following methods explore all concrete states. (provide a short to-the-point explanation.)

- A. Inductive Incremental Verification (IC3)
- B. SAT-based bounded model checking as in [bmc]
- C. BDD-based symbolic model checking
- D. The CEGAR approach as in [car]
- E. The model checker TAPAAL for Timed-arc Petri Nets from [tpn]
- F. The Software Model Checker VeriSoft [smc]
- G. The multi-core model checker from [mcr] (in BFS mode)