

## UNIVERSITY OF TWENTE

Department of Electrical Engineering, Mathematics and Computer Science

**Solution exam Linear Algebra on Friday March 29, 2019, 13.45 – 15.45 hours.**

Exercises 1,2,4,8 and 9 only receive points based on the final answer.

Exercises 3,5,6 and 7 require a motivated answer.

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1.

Consider the function  $f$  given by  $f(x) = \alpha e^x + \beta e^{2x} + \gamma e^{-x}$ , where  $\alpha$ ,  $\beta$  and  $\gamma$  are unknown constants.

Determine  $\alpha$ ,  $\beta$  and  $\gamma$  if it is given that

$$f(0) = -1, \quad f'(0) = 5, \quad f''(0) = 5.$$

We obtain:

$$f(0) = \alpha + \beta + \gamma = -1$$

$$f'(0) = \alpha + 2\beta - \gamma = 5$$

$$f''(0) = \alpha + 4\beta + \gamma = 5$$

The augmented matrix associated to the linear system is:

$$\begin{pmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & -1 & 5 \\ 1 & 4 & 1 & 5 \end{pmatrix}$$

Using elementary row operations we get:

$$\begin{pmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & -1 & 5 \\ 1 & 4 & 1 & 5 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & -2 & 6 \\ 0 & 3 & 0 & 6 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 3 & -7 \\ 0 & 1 & -2 & 6 \\ 0 & 0 & 6 & -12 \end{pmatrix} \\ \sim \begin{pmatrix} 1 & 0 & 3 & -7 \\ 0 & 1 & -2 & 6 \\ 0 & 0 & 1 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -2 \end{pmatrix}$$

The simplified system is:

$$\alpha = -1$$

$$\beta = 2$$

$$\gamma = -2$$

which yields the requested answer.

2.

The matrix  $A$  is given by:

$$A = \begin{pmatrix} -3 & 0 & -1 \\ 1 & 1 & 2 \\ 5 & 0 & 1 \end{pmatrix}$$

a) Determine  $\det A$ .

Expanding along the second column we get:

$$\det A = 1 \cdot \det \begin{pmatrix} -3 & -1 \\ 5 & 1 \end{pmatrix} = -3 + 5 = 2.$$

b)  $A$  has eigenvalue 1 (you don't have to prove this).

Determine the corresponding eigenspace.

We need to find all  $\mathbf{x} \neq 0$  such that

$$A\mathbf{x} = \mathbf{x}$$

or

$$(A - I)\mathbf{x} = \mathbf{0}$$

We have:

$$\begin{aligned} A - I &= \begin{pmatrix} -4 & 0 & -1 \\ 1 & 0 & 2 \\ 5 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 5 & 0 & 0 \\ -4 & 0 & -1 \\ 1 & 0 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 \\ -4 & 0 & -1 \\ 1 & 0 & 2 \end{pmatrix} \\ &\sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

which yields:

$$E_1 = \text{Null}(A - I) = \text{Span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

b) Determine the other (possibly complex) eigenvalue(s) of  $A$ .

We have the following characteristic equation:

$$\begin{aligned} 0 = \det(A - \lambda I) &= \det \begin{pmatrix} -3-\lambda & 0 & -1 \\ 1 & 1-\lambda & 2 \\ 5 & 0 & 1-\lambda \end{pmatrix} = (1-\lambda) \det \begin{pmatrix} -3-\lambda & -1 \\ 5 & 1-\lambda \end{pmatrix} \\ &= (1-\lambda) [(-3-\lambda)(1-\lambda) + 5] = (1-\lambda)(\lambda^2 + 2\lambda + 2) \end{aligned}$$

Therefore the eigenvalues are given by

$$\lambda = 1 \quad \text{or} \quad \lambda^2 + 2\lambda + 2 = 0$$

which yields that the other two eigenvalues are  $-1 + i$  and  $-1 - i$ .

3.

Consider the matrices

$$A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} \quad \text{and} \quad C = \begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix}$$

Verify whether  $A^3 B^5 C^7$  is invertible.

We have:

$$\det A = 1 + 1 = 2, \quad \det B = 3 - 4 = -1, \quad \det C = 4 - 4 = 0$$

But then:

$$\det(A^3 B^5 C^7) = (\det A)^3 (\det B)^5 (\det C)^7 = 2^3 (-1)^5 0^7 = 0$$

Therefore  $A^3 B^5 C^7$  is not invertible.

4.

Given is the matrix

$$A = \begin{pmatrix} 1 & 2 & -3 \\ 1 & 1 & -1 \\ -1 & 2 & -5 \end{pmatrix}.$$

a) Determine Null  $A$ .

We have:

$$A \sim \begin{pmatrix} 1 & 2 & -3 \\ 0 & -1 & 2 \\ 0 & 4 & -8 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & -3 \\ 0 & 1 & -2 \\ 0 & 1 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{pmatrix}$$

which yields:

$$x_1 + x_3 = 0$$

$$x_2 - 2x_3 = 0$$

It is then easily seen that:

$$\text{Null } A = \text{Span} \left\{ \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} \right\}$$

b) Determine Col  $A$ .

We have the following reduced echelon form for  $A$ :

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{pmatrix}$$

which has pivots in the first two columns. Hence Col  $A$  is the span of the first two columns of the matrix  $A$ :

$$\text{Col } A = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \right\}$$

5.

Consider a vector space and two vectors in  $\mathbb{R}^3$ :

$$\mathcal{T} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \right\} \quad \mathbf{v}_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} -3 \\ 0 \\ -2 \end{pmatrix}.$$

Determine whether  $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2\}$ , is a basis for  $\mathcal{T}$ .

We basically need to verify two things. Firstly, whether the vectors in  $\mathcal{B}$  are linearly independent. But this is easily seen since  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are clearly not linear multiples of each other. Secondly we need to verify whether

$$\text{Span } \mathcal{B} = \mathcal{T}$$

$\mathcal{T}$  is spanned by two vectors which we call  $\mathbf{t}_1$  and  $\mathbf{t}_2$ . Note that

$$\text{Span } \mathcal{B} \subset \mathcal{T}$$

if the matrix with columns  $\mathbf{t}_1, \mathbf{t}_2, \mathbf{v}_1, \mathbf{v}_2$  has only pivots in the first columns since then both  $\mathbf{v}_1$  and  $\mathbf{v}_2$  can be expressed in terms of  $\mathbf{t}_1$  and  $\mathbf{t}_2$ . We have:

$$\begin{pmatrix} 1 & 2 & -1 & -3 \\ 2 & 1 & 1 & 0 \\ 2 & 2 & 0 & -2 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & -1 & -3 \\ 0 & -3 & 3 & 6 \\ 0 & -2 & 2 & 4 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & -1 & -3 \\ 0 & -3 & 3 & 6 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Clearly, we only have pivots in the first two columns and hence  $\text{Span } \mathcal{B} \subset \mathcal{T}$ . Remains to show that

$$\mathcal{T} \subset \text{Span } \mathcal{B}.$$

Again we see that this is true if the matrix with columns  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{t}_1, \mathbf{t}_2$  has only pivots in the first columns since then both  $\mathbf{t}_1$  and  $\mathbf{t}_2$  can be expressed in terms of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . We have:

$$\begin{pmatrix} -1 & -3 & 1 & 2 \\ 1 & 0 & 2 & 1 \\ 0 & -2 & 2 & 2 \end{pmatrix} \sim \begin{pmatrix} -1 & -3 & 1 & 2 \\ 0 & -3 & 3 & 3 \\ 0 & -2 & 2 & 2 \end{pmatrix} \sim \begin{pmatrix} -1 & -3 & 1 & 2 \\ 0 & -3 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Clearly, we only have pivots in the first two columns and hence  $\text{Span } \mathcal{B} \subset \mathcal{T}$ . Hence  $\mathcal{B}$  is a basis for  $\mathcal{T}$ .

6.

Determine two different echelon forms for the following matrix:

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 1 & 2 \\ 1 & 1 & 1 \end{pmatrix}.$$

We have:

$$A \sim \begin{pmatrix} 1 & 2 & 1 \\ 0 & -1 & 1 \\ 0 & -1 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 1 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{pmatrix}$$

The last matrix is clearly an echelon form but not a reduced echelon form. We can simply take one more step towards the reduced echelon form and get:

$$A \sim \begin{pmatrix} 1 & 2 & 1 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

and we obtain a second echelon form for the matrix  $A$  which is clearly different from the first one.

7.

Given are four vectors in  $\mathbb{R}^3$ :

$$\mathbf{v}_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \quad \mathbf{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \mathbf{v}_4 = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}.$$

In this case  $\mathcal{T} = \{ \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \}$  is a basis for  $\mathbb{R}^3$ . Determine  $[\mathbf{v}_4]_{\mathcal{T}}$ .

We get:

$$\begin{aligned} \left( \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & 2 & 1 & 1 \\ -1 & 1 & 1 & -1 \end{array} \right) &\sim \left( \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & 2 & 1 & 1 \\ 0 & 2 & 2 & 1 \end{array} \right) \sim \left( \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{array} \right) \sim \left( \begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 2 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{array} \right) \\ &\sim \left( \begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \end{array} \right) \sim \left( \begin{array}{ccc|c} 1 & 0 & 0 & \frac{3}{2} \\ 0 & 1 & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \end{array} \right) \end{aligned}$$

and hence:

$$[\mathbf{v}_4]_{\mathcal{T}} = \frac{1}{2} \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}.$$

8.

Let  $T$  be an arbitrary linear transformation from  $\mathbb{R}^n$  to  $\mathbb{R}^n$ .

a) Assume that  $T$  is one-to-one. Show that  $T^2$  is one-to-one.

Assume  $T^2\mathbf{x} = \mathbf{0}$ , i.e.  $T(T\mathbf{x}) = \mathbf{0}$ . Since  $T$  is one-to-one we find  $T\mathbf{x} = \mathbf{0}$ . But using that  $T$  is one-to-one again we find that  $\mathbf{x} = \mathbf{0}$ . This yields that  $T^2$  is one-to-one.

b) Assume that  $T^2$  is one-to-one. Show that  $T$  is one-to-one.

Assume  $T\mathbf{x} = \mathbf{0}$ . This clearly implies that  $T^2\mathbf{x} = \mathbf{0}$ . But then using that  $T^2$  is one-to-one we find that  $\mathbf{x} = \mathbf{0}$ . This yields that  $T$  is one-to-one.

9.

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  is a linear transformation such that:

$$T \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$T \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$$

Determine the representation matrix of  $T$ .

Note that

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

We compute the image of the standard basis vectors. We get, using linearity:

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2 \cdot T \begin{pmatrix} 1 \\ 1 \end{pmatrix} - T \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} - \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -1 \\ 3 \\ 3 \end{pmatrix}$$

and

$$T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = T \begin{pmatrix} 1 \\ 2 \end{pmatrix} - T \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ -2 \end{pmatrix}$$

We find:

$$[T] = \begin{pmatrix} -1 & 2 \\ 3 & -1 \\ 3 & -2 \end{pmatrix}.$$